E	7	E	1	Q
		U	T	O

P	a	ges	3)
14	a	500	U

Reg.	No
------	----

Nam	0			

B.Sc. DEGREE (C.B.C.S.S.) EXAMINATION, MARCH 2014

Sixth Semester

Core Course—COMPUTATIONAL PHYSICS

(Common for Model-I B.Sc. Physics, Model-II B.Sc. Physics and B.Sc. Physics – E.E.M)

Time: Three Hours

Maximum Weight: 25

Part A

Answer all questions. Objective type questions. Weight 1 for each bunch.

	Bunch I						
1.	1. A group of four bits is ———.						
	(a)	byte.	(b)	bit.			
	(c)	nibble.	(d)	word.			
2.		- device is commonly used as a dri	ver f	or the address bus in a bus oriented system.			
	(a)	Line receiver.	(b)	octal bus transceiver.			
	(c)	interfacing devices.	(d)	buffer device.			
3.		- is place In between the CPU and	the	main memory.			
	(a)	CCD memory.	(b)	cache memory.			
	(c)	Magnetic core memory.	(d)	flash memory.			
4.	4. By default, member of the class in a, C++ program is ———.						
	(a)	public.	(b)	private.			
	(c)	protected.	(d)	none of these.			
	Bunch II						
5.	5. # Include <string .h=""> is a:</string>						
	(a)	pre processor directive.	(b)	header file.			
	(c)	string handling function.	(d)	none of these.			
6.	6. The command used in 8085 micro processor to step the execution and enters the wait state :						
	(a)	MVI.	(b)	NOP.			
	(c)	HLT.	(d)	OUT.			

7.	EPRO	M stands for:				
	(a)	Electrically programmable	ROM.			
	(b)	Erasable programmable R	OM.	Mary 1 - Control of the Control of t		
	(c)	Evolutionary programmab	le ROM.			
8.	The fir	st order R-K method is know	n as ——			
			Bunch	III		
9.	The	is not on entry contr	olled loop.			
	(a)	do while.	(b)	while.		
	(c)	ifelse.	(d)	none of these.		
10.	Class i	s ———.				
	(a)	Built in data type.	(b)	derived data type.		
	(c)	user-defined data type.	(d)	none of these.		
11.	Which instruction enables the programmer to set up continuous loops in 8085.					
	• (a)	Unconditional jumb.	(b)	Call instructions.		
	(c)	Return instructions.	(d)	Restart instructions.		
12.	Which	one of the following is a vola	tile memory	7?		
	(a)	RAM.	(b)	ROM.		
	(c)	Magnetic memory.	(d)	none of these.		
			BUNCH			
13.	In C++	, The function within a class	is called:			
	(a)	Member function.	(b)	private function.		
	(c)	derived function.	(d)	none of these.		
14.	The bin	nding of data and function to	gether in to	single class type variable is a referred to as a:		
	(a)	dynamic binding.	(b)	Encapsulation.		
	(c)	polymorphism.	(d)	inheritance.		
15.	Group	of bidirectional lines used to	transfer da	ta between the CPU and peripherals.		
	(a)	Address bus.	(b)	data bus.		
	(c)	control bus.	(d)	none of these.		
16.	The —	is a logic circuit that a	implifies the	e current or power.		
				$(4 \times 1 = 4)$		

Part B

Answer any **five** questions. Short answer questions (weight 1 each).

- 17. What is absolute and partial encoding?
- 18. Explain the advantages of an assembly language over high-level language.
- 19. Explain the difference between a compiler and an interpreter.
- 20. Draw a schematic diagram of a digital computer.
- 21. State the difference between while and do...... while loop.
- 22. How is a function of a class defined?
- 23. Explain RAM.
- 24. State trapezoidal rule.

 $(5 \times 1 = 5)$

Part C

Answer any four questions. Short Essay / Problems (weight 2 each).

- 25. Explain about dynamic debugging in 8085.
- 26. What is meant by 2 address format, 1 address format and 0 address format?
- 27. What do you understand by main memory, second memory and cache memory?
- 28. Differentiate array and a structure.
- 29. What are objects? How are they created?
- 30. Find the real root of equation $f(n) = x^3 x 1$ using bisection method.

 $(4 \times 2 = 8)$

Part D

Answer any two questions. Essay (weight 4 each).

- Explain different types of instructions in 8085.
- 32. Write a c++ program to sort an array using class.
- 33. Evaluate $\sqrt{12}$ to 4 places of decimal using N-R Method.

 $(2 \times 4 = 8)$